

Closed book. No calculators are to be used for this quiz.
Quiz duration: 15 minutes

Name:

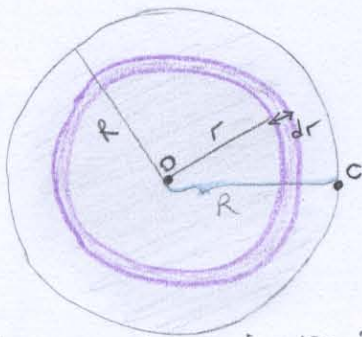
Student ID:

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Find the moment of inertia of a uniform circular disk, of mass M and radius R , about an axis perpendicular to the disk at its edge, at distance R from the center of the disk.

We calculate I_c from I_o
using the parallel-axis theorem

Let's find I_o , rotating about an axis perpendicular to the disk at its center.



The moment of inertia is $I = \int r^2 dm = \int dI$

$dm = \rho dA$,
Mass element has an area as shown with radius r and thickness dr
 $dA = 2\pi r dr$ $\rho = \frac{M}{A} = \frac{M}{\pi R^2} = \frac{dm}{dA}$ ρ : mass per unit volume

$$\Rightarrow I_o = \int_0^R r^2 \cdot \rho \cdot 2\pi r dr = 2\pi \rho \int_0^R r^3 dr = 2\pi \rho \left[\frac{r^4}{4} \right]_0^R = 2\pi \rho \frac{R^4}{4}$$

$$\Rightarrow I_o = 2\pi \cdot \frac{M}{\pi R^2} \cdot \frac{R^4}{4} = \frac{1}{2} MR^2 \quad \text{check from Table 9.2, case (f)}$$

$$\Rightarrow I_c = I_o + MR^2 \quad (\text{parallel axis theorem})$$

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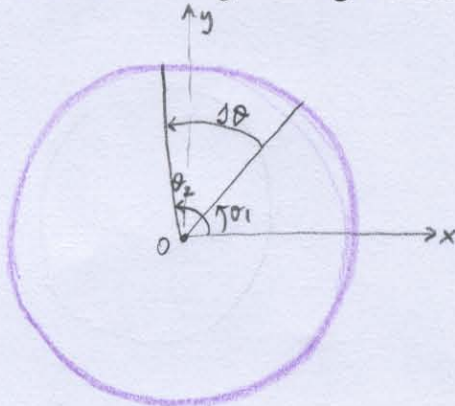
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A disk of mass M and radius R is rotating about a central perpendicular axis. Its initial angular velocity ω_0 is doubled after a time τ . Assuming constant acceleration determine the angle through which the disk rotates in τ .



If the angular acceleration is constant, then θ , ω_z and d_z are related by simple kinematic equations analogous to those for straight-line motion with constant linear acceleration.

$$\omega_z = \omega_{0z} + \alpha_z \cdot t \quad \Rightarrow \quad \omega_{0z} = \alpha_z \cdot \tau \quad \Rightarrow \quad \alpha_z = \frac{\omega_{0z}}{\tau}, \text{ constant}$$

$$\Rightarrow \theta - \theta_0 = \Delta\theta = \frac{1}{2} (\omega_{0z} + \omega_z) \cdot \tau \quad \Rightarrow \quad \Delta\theta = \frac{1}{2} (3\omega_{0z}) \cdot \tau //$$

or

$$\omega_z^2 = \omega_{0z}^2 + 2\alpha_z \cdot \Delta\theta \quad \Rightarrow \quad 4\omega_{0z}^2 = \omega_{0z}^2 + 2 \cdot \left(\frac{\omega_{0z}}{\tau} \right) \cdot \Delta\theta$$

$$\Delta\theta = \frac{3\omega_{0z}^2 \cdot \tau}{2\omega_{0z}} = \frac{3}{2} \omega_{0z} \cdot \tau //$$

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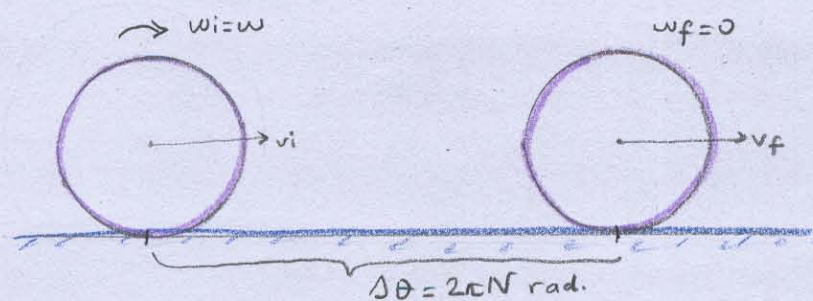
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How much average power is dissipated when a wheel of radius R and mass M is brought to rest in N revolutions, with a constant angular acceleration, from an angular initial velocity ω ?



$v = R\omega$
(We assume that there is a rotation without slipping)

$$\begin{aligned} \Delta W &= \Delta KE_{\text{rot}} + \Delta KE_{\text{translation}} \\ &= \left(\frac{1}{2} I \omega_f^2 - \frac{1}{2} I \omega_i^2 \right) + \left(\frac{1}{2} M v_f^2 - \frac{1}{2} M v_i^2 \right) \\ &= -\frac{1}{2} \left(\frac{1}{2} M R^2 \right) \omega^2 + \left(-\frac{1}{2} M (R\omega)^2 \right) \end{aligned}$$

$$\Rightarrow \Delta W = \Delta KE = -\frac{3}{4} M R^2 \omega^2$$

where $I = \frac{1}{2} M R^2$ (Table 9.2 case (f)). We take $\Delta U = 0$

let's find Δt

$$\theta - \theta_0 = \frac{1}{2} (\omega_i + \omega_f) \cdot \Delta t \quad (\text{since } \alpha \text{ constant})$$

$$\Rightarrow 2\pi N = \frac{1}{2} \omega \cdot \Delta t$$

$$\Rightarrow \Delta t = \frac{4\pi N}{\omega}$$

$$P_{\text{ave}} = \frac{\Delta W}{\Delta t} = \frac{-\frac{3}{4} M R^2 \omega^2}{4\pi N / \omega} = -\frac{3 M R^2 \omega^3}{16 \pi N}$$

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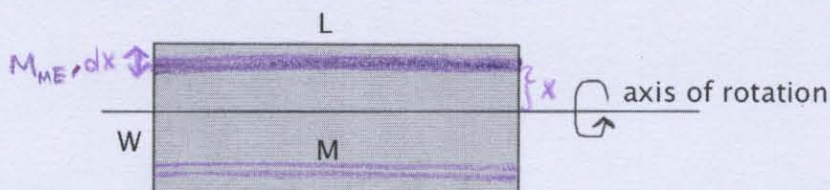
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Find the moment of inertia of a thin rectangular uniform sheet of metal, of mass M , length L and width w , about the axis shown in the figure.



Check the solutions of the quizzes of the last years (2007, 2008, ...).

Let's calculate the moment of inertia I of a uniform solid infinitely thin sheet of metal with mass M_{ME} , as a mass element, at a distance x from the rotating axis.

$$I_{NE} = I_{\text{mass Element}} = \int x^2 dm$$

As the rod is infinitely thin, every point on it has the same distance to the rotating axis.

$$I_{M.E} = \int x^2 dm = x^2 \int dm = M_{\text{mass Element}} x^2$$

$$M_{\text{mass Element}} = \frac{M}{w \cdot L} \cdot L \cdot dx = \rho \cdot L \cdot dx \quad \leftarrow \quad \rho = \frac{M}{w \cdot L} = \frac{M \cdot E}{L \cdot dx}$$

Then integrate the infinitely thin rod to find the total moment of inertia.

$$I = \int I_{ME} = \int_{-w/2}^{w/2} x^2 \cdot \rho \cdot L \cdot dx = \rho \cdot L \left[\frac{x^3}{3} \right]_{-w/2}^{w/2} = \frac{\rho L}{3} \left[\frac{w^3}{8} - \left(-\frac{w^3}{8} \right) \right]$$

$$I = \frac{\rho \cdot L}{3} \frac{w^3}{4} = \frac{M}{w \cdot L} \cdot \frac{L}{3} \cdot \frac{w^3}{4} = \frac{M w^2}{12}$$

You can check the solution from Table 9.2, case (d) and parallel axis theorem. The moment of inertia of thin rectangular plate, axis along edge, is given as

$$I_p = \frac{1}{3} M w^2 = \frac{1}{12} M w^2 + M \left(\frac{w}{2} \right)^2$$

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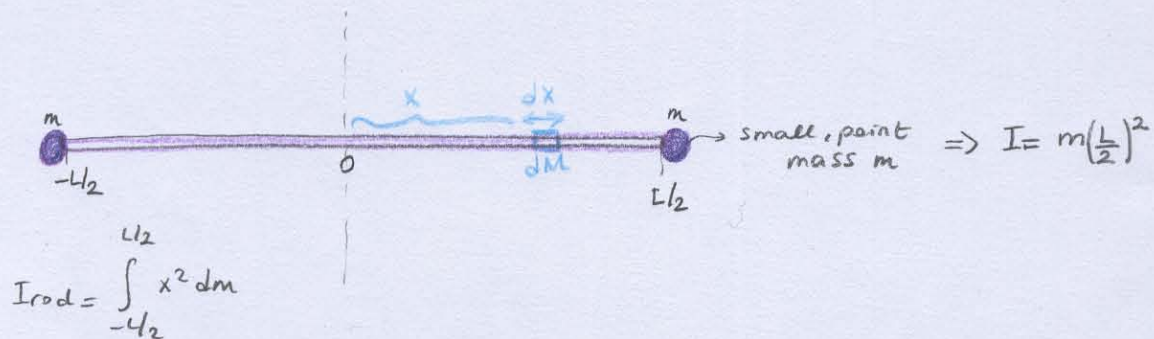
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A rod of mass M and length L connects two small masses m . Find the moment of inertia of the composite system about an axis through the center, perpendicular to the rod.



$$I_{\text{rod}} = \int_{-L/2}^{L/2} x^2 dm$$

$$\rho = \frac{M}{L} = \frac{dm}{dx} \Rightarrow dm = \frac{M}{L} dx$$

$$I_{\text{rod}} = \int_{-L/2}^{L/2} x^2 \frac{M}{L} dx = \frac{M}{L} \left[\frac{x^3}{3} \right]_{-L/2}^{L/2} = \frac{M}{L} \cdot \frac{1}{3} \left[\frac{L^3}{8} - \left(-\frac{L^3}{8} \right) \right] = \frac{ML^2}{12}$$

check from Table 9.2, case (a).

$$I_{\text{total}} = I_{\text{rod}} + 2I_{\text{mass}} = \frac{ML^2}{12} + 2 \cdot \frac{mL^2}{4} = \frac{7ML^2}{12}$$